The Effects of Ignition Advance on Cylinder Head Temperature, Speed, and Efficiency

If a little is good, more is better, and too much should be just about right. Not!

Electronic Ignition (EI) systems are becoming increasingly popular on Experimental aircraft, with frequently touted benefits including: easier starting, smoother operation, reduced plug fowling, less carbon buildup in the cylinders, lower maintenance, the ability to use inexpensive automotive spark plugs, increased performance, and efficiency. These gains are possible due to the higher energy spark (greater intensity and/or longer duration) and variable advance timing used by most EI systems. My Van's RV-8 has a four-cylinder Lycoming with 10:1 compression ratio and mechanical fuel injection with balanced injector nozzles. It is also equipped with dual P-MAG Ignition (www.emagair.com) and an EI Commander (*www.eicommander.com*) that allows the user to vary the maximum ignition advance and to shift the timing map. To quantify the effect of varying the ignition timing, I conducted

an experiment across a wide range of ignition advance settings, altitudes, and mixtures. My goal was to define the optimum advance map for my engine. This article only looks at the effects of ignition timing on CHT, speed, and efficiency. Analysis of the other potential advantages of EI is left for another day.

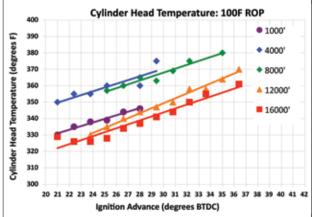


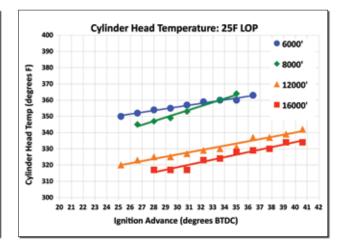
El Commander showing max advance and advance shift.

BY NIGEL SPEEDY

When to Spark?

Most EI systems use a combination of manifold absolute pressure (MAP) and engine speed (rpm) as inputs to calculate the ignition advance setting. Optimum ignition timing would occur when the mixture is ignited sufficiently before top dead center (BTDC) so that the peak combustion pressure (PCP) occurs around 17 degrees after top dead center (ATDC). Too much ignition advance and the PCP will occur too close to TDC, resulting in high peak pressures, possible detonation, and high stress on the engine. Not enough advance and PCP will occur too far ATDC when the piston is moving rapidly down the cylinder, resulting in low power. In general, lean of peak (LOP) mixtures and low MAP reduces the flame speed, so these conditions require more ignition advance than ROP mixtures and high MAP to achieve optimum PCP timing.





CHT LOP vs. ignition advance.

CHT ROP vs. ignition advance.

Test Method and Conditions

For my experiment, every test point was in level flight with wide open throttle (WOT), propeller set to 2500 rpm, and the mixture constant. I tested at a range of pressure altitudes from 1000 feet to 16,000 feet. I used mixtures of 100° F ROP and 25° F LOP (LOP only at or above 6000 feet). At each test condition, I adjusted the ignition timing and measured the true airspeed (TAS) and cylinder head temperature (CHT). I varied the timing from as little as 21 degrees to as much as 40.6 degrees BTDC (although not at every altitude). This range seemed adventurous enough given that my engine data plate timing is 25 degrees. The higher the power setting, the less I deviated from 25 degrees advance. For most test points, adjusting the maximum advance setting was sufficient to achieve the desired value. At high altitude, to achieve the large advance values, I had to

use a combination of maximum advance and advance shift on the EI Commander. The TAS was used as an indication of engine power, and the CHT as an indication of engine stress. Changes in TAS due to timing were relatively small, so smooth air was required for good data. The engine required 5 minutes to thermally stabilize, so patience was required to accurately measure the effect of timing on CHT. I determined the optimum timing under each condition to be the value that gave the highest TAS with the lowest CHT. As the throttle, prop, and mixture were constant for each test run, so was the fuel flow. Thus TAS was not only an indication of power, but efficiency as well. Overall I flew 10 hours and completed 80 separate test points.

Cylinder Head Temperature

The most obvious effect of changing ignition timing, all other things constant,

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was on the CHT. In every case, increasing the advance resulted in higher CHT. The rate of increase was approximately linear. When the mixture was 100° F ROP, the average CHT increase was 2.5° F per degree of ignition advance. When the mixture was 25° F LOP, the average CHT increase was slightly less at 1.6° F per degree of ignition advance.

True Airspeed

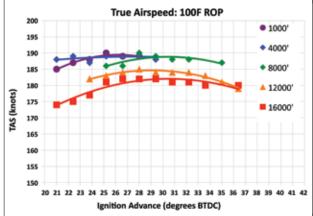
True Airspeed: 25F LOP

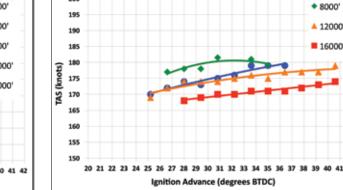
Changing ignition timing also affected the aircraft TAS. Under each condition, the highest speed was achieved at some optimum timing value. Less than the optimum timing resulted in slower speeds. More than the optimum timing also resulted in slower speeds. This characteristic behavior was easier to see at high power. With LOP mixtures and low MAP, the TAS increased with increasing advance. At 12,000 feet and 16,000 feet, I reached my self-imposed

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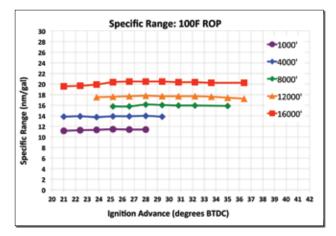
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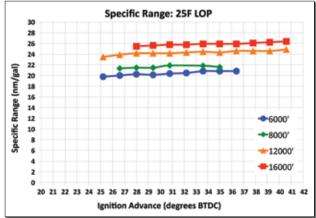




TAS ROP vs. ignition advance.







Specific range LOP vs. ignition advance.

Specific range ROP vs. ignition advance.

test limit of 40.6 degrees advance before a clear peak in TAS versus ignition timing was observed. The potential increase in speed due to optimized timing was made by comparing the speed at 25 degrees ignition advance. When ROP, the speed increases were quite small. The greatest increase ROP was at 8000 feet, where speed increased from 186 to 190 TAS when going from 25 degrees to 28 degrees ignition advance (a 2% gain in speed). As speed is proportional to power cubed, this would equate to a 6.6% increase in power. LOP the increases were larger. The greatest increase LOP was at 12,000 feet where the speed increased from 169 to 179 TAS as timing was increased from 25 degrees to 40.6 degrees ignition advance (a 5.9% gain in speed). This equates to an 18.8% increase in power. The curves for speed versus timing had relatively flat peaks. This meant that the speed penalty for using less than the optimum ignition advance was small. Given that the CHT always increased with increased timing, it was much better to err on the side of less. rather than more, advance.

If the optimum timing at each altitude is compared, a few things become clear. First, the optimum ignition timing was quite different ROP and LOP. When ROP, the optimum ignition timing was approximately 25 degrees, and this varied little with altitude. Even at 16,000 feet, the optimum ignition timing when 100° F ROP was only 28 degrees. Second, when LOP the optimum ignition timing was greater than when ROP; however, the difference was not constant. As power was reduced, LOP required progressively more advance than ROP. This means that a simple LOP/ROP switch that adds a fixed amount of advance would not result in optimal timing. It would be a better compromise though. Third, when LOP the optimum ignition timing increased significantly as MAP was reduced, starting at around 32 degrees ignition advance at 6000 feet (24.3 inches MAP), up to 40.6 degrees ignition advance at 12,000 feet (19 inches MAP).

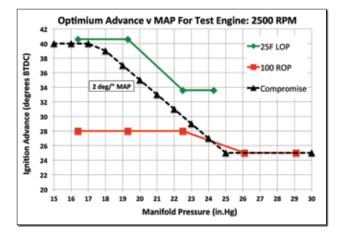
Efficiency

An advertised advantage of electronic ignition is that the high-energy spark, in conjunction with variable and more highly optimized timing, results in "substantial" increases in efficiency. A quick internet search yields claims on the order of 10–15%. We normally think of efficiency as specific range, measured in units of nm/gal, which is the same as TAS/fuel flow (nm per hour/gal per hour). In my experiment, the fuel flow was constant for each test run. The ignition advance that resulted in the highest speed also resulted in the highest specific range. When the specific range was compared with the specific range achieved at 25 degrees ignition timing (baseline for my engine), it was possible to isolate the improvement in efficiency due to optimized timing alone. When ROP, the average improvement in efficiency due to optimized timing was 1%. When LOP, the improvement in

efficiency was slightly higher, averaging 4.3%. The greatest improvement I saw was only 5.9%, which shows that ignition timing is not a significant factor in increased economy. Efficiency was improved more by simply climbing 4000 feet than optimizing the timing at any given altitude. Repeating this test keeping TAS constant (by adjusting throttle) and measuring fuel flow versus timing advance had the same outcome.

Optimum Advance Curve

When considering an optimum ignition advance curve, it is necessary to consider the mixture as well as rpm and MAP. The Lycoming IO-360 Operator's Manual recommends leaning only when less than 75% power. For an engine rated at 2700 rpm and being operated at 2500 rpm, WOT and ROP, this will occur at around 24 inches MAP or 6000 feet. Let's assume we operate ROP above 24 inches MAP and LOP below 24 inches MAP. Taking into account the optimum ignition advance results obtained and the operational requirement to transition from ROP to LOP, a best compromise curve for my engine would have a constant 25 degrees ignition advance above 25 inches MAP, at which point timing would increase at a rate of 2% per inch of MAP reduction, up to a maximum of 40 degrees advance at 17 inches MAP. I say a compromise, as my ignition system does not automatically compensate for mixture and has a single map that must work acceptably for both ROP and LOP conditions.



Ignition Timing	СНТ	Speed	Efficiency	Comments
Less than optimum	Cooler	Slower	Lower	Lower stress and safe, but inefficient.
Optimum	Normal	Faster	Higher	Safe, fast, and efficient.
More than optimum	Hotter	Slower	Lower	Higher stress, lower detonation margin, slower, and inefficient.

Optimum advance vs. manifold pressure.

Safety

There are a few safety considerations to think about if you embark upon an ignition timing experiment, especially if it involves changing the timing while the engine is running or in flight. If you command an ignition advance setting that is not compatible with the engine's current operating regime, it may do one or more unpleasant things. It could run rough, stop, or be driven into detonation, which could quickly lead to pre-ignition and subsequent failure. To reduce the risk, you may consider implementing some or all of the following strategies that I used.

- Research the effects of ignition timing on internal combustion engines. Practice your method of changing ignition timing on the ground so that you can do it quickly under pressure.
- Have a tried-and-tested ignition map saved so that you can quickly return to it if you ask for an inappropriate timing value or the system malfunctions and commands an inappropriate timing value.
- Only make an ignition timing change where you can execute a successful forced landing. Practice forced landings before you start experimenting with ignition timing.
- Understand what detonation is going to look like on your engine monitor. Have a plan you have practiced in the event that you encounter detonation (throttle idle, prop full forward, mixture full rich, dive to increase cooling airflow, and change timing is a place to start).

• If you have an engine monitor, con-

Summary of test results.

sider lowering the CHT alarm limits during testing, as rapidly rising CHT is a sure sign of engine unhappiness. The sooner you see the CHT rising, the sooner you can combat the problem.

Before commencing an ignition timing experiment, you should also consider how you fly your plane and the risk vs. reward. The likely reward is low single-digit percentage increases in speed and efficiency, but the risk is high CHT and potential catastrophic engine damage. There are much more fertile places to look for improvements before you consider ignition timing. In my aircraft, flying at 18,000 feet improves efficiency by approximately 25% compared to 1000 feet. Similarly, running LOP vs. ROP under any condition also improves efficiency by about 25%. Even though I have a constant-speed propeller, I see as much as 7% increase in TAS at constant MAP and fuel flow by choosing the optimum rpm. If you fly ROP there is very little to be gained by changing timing. LOP the gains due to ignition advance are larger, but still small in the grand scheme of things.

The gains from varying just the ignition timing are real, but small. Most of the efficiency advantage of EI systems likely comes from a higher energy and longer duration spark that allows LOP mixtures to be ignited reliably at high altitude. Once you can ignite a LOP mixture, subsequently varying the timing only has a small impact. If you change from magnetos to EI, you will

see the benefits of higher intensity spark and timing, whereas in this experiment, I already had EI and just varied the timing. More ignition advance increases CHT. It is not possible to have optimum ignition timing based on rpm and MAP alone; the mixture must be considered. LOP mixtures require a greater variation in timing due to changes in MAP than ROP mixtures. The difference between optimum ROP and LOP ignition timing is not constant. When it comes to ignition advance, too much is not just about right. It is much better to err on the side of less ignition advance. The methods presented and the data shown here are just one way to conduct an engine timing experiment. The values shown are meant to provide a general indication of the effects of varying timing, not to provide an ideal timing map for every engine. The advance values shown here could be safe in your engine, but they could just as easily result in a catastrophic failure. +

Nigel Speedy started flying GEL

helicopters with the Australian Army and is a graduate of the U.S. Naval Test Pilot School. He currently instructs at the National Test Pilot School in Mojave, California. Nigel enjoys flying his Van's RV-8 and the freedom of E/A-B to experiment.

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